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PIC18	F4550					
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Abstrac	t	Abstract:				
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I. Prelimina	iry	design and application of electromyography or more	commonly known as gauges muscl	e tension to	o move the	e robot a
II. Theoretic	cal Basis	the aid of a microcontroller PIC18F4550, with this fination in the form of graphs or audio into physical form of m		cles signals	s that are ι	isually p
III. Hardwai	re & Software Desi	gn				
IV. Conclus	sion	Published in: 2016 3rd International Conference on	Information Technology, Computer,	and Electr	ical Engine	ering (I
Authors		Date of Conference: 19-20 October 2016	INSPEC Accession Nu	ession Number: 16791785		
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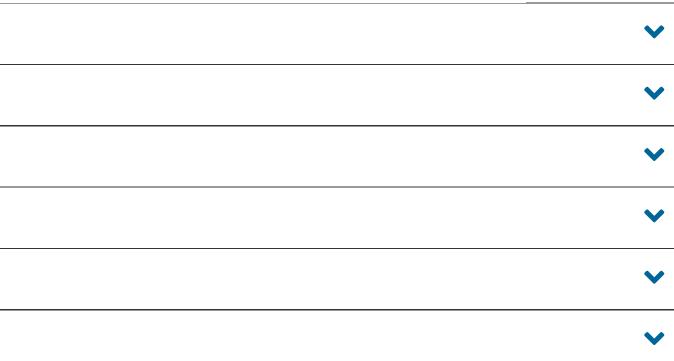
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